

# User Manual: NexBot Robotics STP113-007 Stepper Motor

SKU: NXB-SRV-STP113-007 | Version: 1.0 | Brand: NexBot Robotics

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## 1. Safety Information

**READ ALL SAFETY INSTRUCTIONS BEFORE OPERATION.** Failure to follow safety procedures may result in serious injury or equipment damage.

**DANGER:** Isolate all hazardous energy before servicing NexBot Robotics STP113-007 Stepper Motor; stored electrical or mechanical energy may remain present after shutdown.

**WARNING:** Operate NXB-SRV-STP113-007 only within its intended Drive Systems > Servo Motors > Stepper Motors duty profile and published specification limits.

**CAUTION:** Use only approved tools, mating parts, and installation hardware to prevent premature wear or unsafe operation.

**NOTICE:** Protect the product from contamination, impact, and environmental exposure beyond IP67 during installation and service.

## 2. Product Overview

NexBot Robotics STP113-007 Stepper Motor (NXB-SRV-STP113-007) is a stepper motor used in industrial robotics equipment where category-specific fit, electrical

or mechanical compatibility, and predictable serviceability are important to buyers. The product should be understood as the exact component named by its category path, not as a complete robot or a generic service item. It supports installation, replacement, and maintenance workflows in robotic production cells by giving procurement and maintenance teams a clearly defined part class, relevant engineering specifications, and application context that matches the actual hardware being purchased.

## 3. Getting Started

### 1. Confirm product identity

Verify the installed item is NexBot Robotics STP113-007 Stepper Motor with SKU NXB-SRV-STP113-007. Cross-check the unit against project documentation before applying power or connecting it to the host system.

### 2. Review operating context

Understand how the product is used within the Drive Systems > Servo Motors > Stepper Motors workflow, including any upstream and downstream dependencies, service intervals, and operator responsibilities.

### 3. Complete initial startup

Power up the unit under controlled conditions, observe indicator states, and verify the product initializes cleanly with the expected 24VDC operating setup.

## 4. Operation

### Normal operation

Run NexBot Robotics STP113-007 Stepper Motor within the documented workload, environmental, and service conditions. Track alarms, unusual noise, heat, or vibration so corrective action can be scheduled before unplanned downtime occurs.

### Interface and controls

Use the supported electrical and control interfaces to commission, monitor, and troubleshoot the device. Validate all signal mappings and control behavior after maintenance or part replacement, especially where GigE Vision communication is required.

**Tip:** Capture a baseline of healthy status indicators after commissioning so later diagnostics can be compared quickly.

### Load and application limits

Keep the product within the published ratings for speed, force, load, and environmental exposure. Where applicable, confirm mounting, routing, and attached tooling do not compromise access, cooling, or serviceability.

### Change management

Whenever hardware, firmware, wiring, or connected tooling changes, repeat the relevant verification and commissioning checks before returning the equipment to production service.

**Tip:** Update maintenance records immediately after any wiring, parameter, or parts change.

## 5. Maintenance Schedule

Interval	Task	Notes
Daily	Inspect NexBot Robotics STP113-007 Stepper Motor for visible wear, damage, contamination, loose hardware, and abnormal status indicators.	Record any abnormalities before the next production cycle begins.
Monthly	Verify mounting integrity, connector condition, and cable routing or strain relief points.	Retorque or reseal hardware only to the documented service specification.
Quarterly	Review diagnostic logs, event history, and operational trends for early signs of degradation.	Escalate recurring warnings before they develop into hard faults.
Annually	Perform a full service inspection covering mechanical condition, electrical connections, and functional verification.	Coordinate annual service with planned downtime to minimize production disruption.

## 6. Troubleshooting

Symptom	Possible Cause	Solution
Unit does not initialize or remain ready	Incoming supply, controls wiring, or commissioning parameters do not match the documented 24VDC configuration.	Verify power quality, wiring continuity, protective devices, and startup parameters before restarting the unit.
Intermittent communication or status loss	Loose connectors, damaged cabling, or interface mismatch on GigE Vision.	Inspect physical connections, confirm interface settings, and replace damaged cables or connectors as needed.
Unexpected wear, vibration, or overheating	Mechanical loading, contamination, misalignment, or duty cycle exceeds the intended application conditions.	Inspect the installation, restore proper alignment and cooling, and verify the product is being used within its published operating limits.
Connected equipment performance is inconsistent	The installed product is not configured correctly for the host system or compatible robot series (R-20, C-10, S-5).	Validate the configuration, confirm compatibility, and rerun the functional verification procedure after any corrections.

## 7. Technical Specifications

Parameter	Value	Unit
Weight	0.45	kg
Material	Anodized Aluminum	
Voltage	24VDC	
IP Rating	IP67	
Country of Origin	US	
Protocol	GigE Vision	
Dimensions	65 x 65 x 48 mm	
Torque	7 Nm	