

# User Manual: NexBot Vision 642-003 Ceiling Or Wall Robot Mount

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## 1. Safety Information

**READ ALL SAFETY INSTRUCTIONS BEFORE OPERATION.** Failure to follow safety procedures may result in serious injury or equipment damage.

**DANGER:** An approved structural analysis of the support structure is mandatory before installation. Failure to verify the structure's load capacity can result in collapse, causing death or serious injury.

**WARNING:** Always lock-out and tag-out all energy sources to the robot before performing any inspection, maintenance, or cleaning of the mount. Unexpected robot movement can cause severe injury.

**WARNING:** Do not modify, drill, or weld any part of the NexBot Vision 642-003 mount. Unauthorized modifications will void the warranty and can compromise the structural integrity of the mount.

**CAUTION:** The mount's surfaces may be hot if installed near heat-generating equipment. Allow surfaces to cool before performing maintenance.

**NOTICE:** This mount is constructed from A36 Structural Steel. Ensure that the operating environment is free from corrosive agents that could degrade the material over time.

## 2. Product Overview

The NexBot Vision 642-003 Ceiling Or Wall Robot Mount provides a robust and reliable solution for installing compatible NexBot robots in inverted or horizontal orientations. This heavy-duty mount is designed to maximize production floor space and enable unique operational layouts that are not possible with traditional floor-mounted installations, making it ideal for overhead machine tending, complex assembly lines, and wide-area pick-and-place applications. Constructed from high-strength A36 structural steel with a durable powder-coated finish, the mount ensures exceptional rigidity and long-term stability under continuous industrial use. Its design minimizes vibration, which is critical for maintaining robot accuracy and repeatability during high-speed operations. The precision-machined mounting interface provides a secure and accurate fit for select NexBot R-Series and C-Series robots, ensuring a seamless integration process. With a substantial static load capacity of 250 kg, this mount offers a significant safety margin for a range of robot models and their associated end-of-arm tooling. The 642-003 mount is engineered for versatility, featuring a standardized bolt pattern that aligns perfectly with supported robot bases. This facilitates a straightforward installation process, reducing downtime and integration complexity. By elevating the robot, the mount provides an expanded work envelope and can improve accessibility to machinery and workpieces. This configuration is particularly beneficial in welding, dispensing, and material handling tasks where an unobstructed approach from above is required. Proper installation is critical for safety and performance. The mount must be securely fastened to a suitable load-bearing structure, such as a reinforced concrete ceiling or a structural steel beam, capable of supporting the combined weight of the mount, the robot, and its maximum payload during dynamic movements. All required high-tensile mounting hardware for attaching the robot to the mount is included. Structural anchoring hardware must be sourced separately to match the specific requirements of the installation site.

## 3. Getting Started

### 1. Product Overview

The NexBot Vision 642-003 Ceiling Or Wall Robot Mount is a passive structural component designed to securely affix a compatible NexBot robot in an inverted or horizontal orientation. Its heavy-duty A36 steel construction ensures rigidity and long-term stability for high-precision applications. This mount is intended to free up floor space and enable complex automation cell layouts.

### 2. Intended Use

This product is designed exclusively for mounting specific NexBot robot models within their rated payload and operational limits in an indoor industrial environment. Any other use, including mounting of non-NexBot equipment or use in outdoor or corrosive environments, is considered a misuse of the product.

### 3. Component Identification

Before use, familiarize yourself with the mount's primary components. These include the large square Base Plate which attaches to the building structure, the main Support Column, and the Robot Interface Plate where the robot itself is bolted.

## 4. Operation

### Dynamic Load Management

The mount is designed to withstand the dynamic forces generated during robot operation. To maximize the life of the system, robot motion paths should be programmed with smooth acceleration and deceleration profiles to avoid high-frequency vibrations or sudden shocks.

**Tip:** Utilize corner rounding or blending features in your robot programming to create smoother motion paths, which reduces peak stress on the mounting system.

### Collision Detection

While the mount itself is passive, its fixed position is a critical factor in the robot's safety configuration. Ensure the mount's volume and position are accurately defined in the robot controller's safety software to prevent collisions between the robot arm and its own base.

### Environmental Considerations

The standard powder coated finish provides protection against typical industrial atmospheric conditions. If the mount is to be used in an environment with chemical fumes or high humidity, a more frequent inspection schedule for signs of corrosion is recommended.

### Periodic Observation

Operators should make it a habit to visually observe the mount during robot operation. Report any new or unusual vibrations, noises, or visible shifting to maintenance personnel immediately for further investigation.

## 5. Maintenance Schedule

Interval	Task	Notes
Weekly	Perform a 360-degree visual inspection of the mount. Look for any signs of damage, corrosion, or loose fasteners. Check the integrity of the robot cable management.	This check can be performed from the ground with binoculars if the mount is at a significant height.
Quarterly	Clean all accessible surfaces of the mount with a dry, lint-free cloth to remove dust and debris buildup. For stubborn grime, use a cloth lightly dampened with a mild detergent solution.	Avoid using solvents or abrasive cleaners that could damage the powder coat finish.
Semi-Annually	With the robot locked out, check the torque of the bolts that fasten the robot to the mount's interface plate. Tighten to the robot manufacturer's specification if necessary.	This is a critical check for maintaining robot accuracy and safety.
Annually	A qualified technician must verify the torque of the primary structural bolts	Requires calibrated equipment and adherence to all safety

Interval	Task	Notes
	holding the mount to the building. This is a critical safety inspection.	procedures for working at height.
Annually	Inspect the powder coat finish for any breaches (chips, deep scratches). Address any areas of exposed steel by cleaning and applying a suitable touch-up paint to prevent rust.	Pay close attention to edges and areas around fasteners.

## 6. Troubleshooting

Symptom	Possible Cause	Solution
Increased robot position error or poor repeatability.	One or more fasteners have loosened, causing a micro-shift in the mount's position during operation.	Perform a full torque check on both the robot-to-mount bolts and the mount-to-structure bolts.
A visible gap has appeared between the mount's base and the wall/ceiling.	Catastrophic failure of mounting anchors or the building structure itself. This is a critical failure.	Immediately stop the robot, remove all personnel from the area, and contact a structural engineer and your site safety manager. Do not resume operation.
Creaking or groaning noises are heard from the mount during robot movement.	Slight movement at a fastening point, potentially due to under-torqued bolts.	Stop operation immediately. Lock-out the robot and conduct a full torque check of all structural fasteners.
Robot cables are showing signs of abrasion or wear near the mount.	Improper cable routing is causing them to rub against an edge of the mount during operation.	Re-route cables to ensure they do not contact any sharp edges. Add protective sheathing to the cables if necessary.
Corrosion is visible on the mount's surface.	The powder coat finish has been compromised, exposing the A36 structural steel to moisture.	Mechanically clean the affected area to remove all rust, then apply a zinc-rich primer and a color-matched industrial top coat.
Excessive vibration is felt on the structure far from the robot.	The robot's dynamic load is creating resonance with the building structure. The mounting location may be unsuitable.	Consult a structural engineer. Solutions may include adding bracing to the structure or adjusting robot acceleration parameters to change the frequency of vibration.

## 7. Technical Specifications

Parameter	Value	Unit
Weight	85.5	kg
Material	A36 Structural Steel, Powder Coated	
Country of Origin	SE	
Dimensions	750 x 750 x 400 mm	